#### university of groningen university of groningen 7 faculty of mathematics and natural sciences 02 July 2012 | 1 02 July 2012 | 2 Bachelor Project 2012 Table of Contents Analysis of the Euclidean Feature > Project Goal > Explaining the EFT Transform algorithm > Mechanical Verification Project Progress Sebastian Verschoor > Evaluation > Questions Supervisors: > prof. dr. Gerard R. Renardel de Lavalette > prof. dr. Wim H. Hesselink university of groningen university of groningen omputing science 02 July 2012 | 3 02 July 2012 | 4

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#### The project goal

- > The goal of this bachelor project is to mechanically verify (or even disprove) that the algorithm as posed by Hesselink [1] correctly calculates the Euclidean Feature Transform (EFT), and does so in linear time complexity.
- > Mechanical Verification > Mathematical Proof





#### The EFT algorithm

- > The algorithm uses some clever tricks
  - Iterating the dimensions, using the same algorithm for solving the base case and the inductive step
- Reduces the problem to finding the one-dimensional EFT
- > *O(n)* (*n* number of "pixels")



# The EFT algorithm

OneFT(n, h):	t[q+1] ← n; at[q+1] ← n − 1
$q \leftarrow 0; t[0] \leftarrow 0; at[0] \leftarrow 0$	for $(j \leftarrow 0; j = q; j++)$
for (k ← 1; k < n; k++)	$x1 \leftarrow t[j+1] - 1$
while $(q \ge 0 \land f(t[q], at[q]) > f(t[q], k))$	for $(x \leftarrow t[j]; x = x1; x++)$
$q \leftarrow q - 1$	$FT[x] \leftarrow \{at[j]\}$
if (q < 0)	$\text{for} \ (\textbf{p} \leftarrow \textbf{at}[j] + 1; \ \textbf{p} = \textbf{at}[j+1]; \ \textbf{p}++)$
$q \leftarrow o; at[o] \leftarrow k$	$if(f(x_1, p) = f(x_1, at[j]))$
else	$\mathrm{FT}[\mathrm{x1}] \leftarrow \mathrm{FT}[\mathrm{x1}] \cup \{\mathrm{p}\}$
$w \leftarrow 1 + g(at[q], k)$	
if (w < n)	
$q \leftarrow q+1$	
$t[q] \leftarrow w; at[q] \leftarrow k$	





Welcome to the PVS Specification and Verification System

- Prototype Verification System (PVS 5.0)
  SRI International, Computer Science Laboratory
- Specification Language
- Interactive Prover



### **PVS Specification Language**

- > Based upon simple typed logic
- > Formal specification of the problem
  - Types
  - Definitions
  - Theorems / Lemmas

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#### **PVS** Prover

- Proof obligation
  - Logical sentence:  $P_0 \land P_1 \land \dots \land P_m \Rightarrow Q_0 \lor Q_1 \lor \dots \lor Q_n$
- > Proof commands
  - Rewrite proof obligation to a logical equivalent statement
- > The Prover does not prove anything!
  - It is merely keeps a "smart" administration

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#### **Program Correctness**

- > programs.pvs
  - Hoare-Triplets:
  - {P} S {Q}
  - While loops
    - 5 steps
    - Prove correctness and termination



## PVS Prover - Example

- Interview of mathematics computing science and natural sciences of computing science of the mathematics of the mathematical sciences of the mathematic
  - > Verified the mathematics
  - > The algorithm
    - · Proved on paper
    - Specified in PVS
  - > 118 theorems/lemmas
    - 91 proven



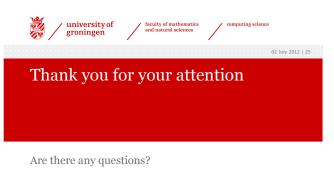
#### Project Progress (todo)

- > Prove the algorithm
- With PVS
- > Optional: prove the mathematics behind iterating the dimensions
- > Write thesis



### Evaluation

- > Mechanically verifying a problem does not *result* in a deeper understanding of a problem
  - It does *require* a full understanding of the problem
- > PVS is a great tool for proving complex mathematical theorems
  - But, often it feels like you do a lot of trivial work that could somehow be automated





#### References

 W. H. Hesselink, "Distance transforms and feature transform sets," May 2009. An extension and modification of the IPL paper.